Vision and Language: A Video Perspective University of Bonn MIT-IBM Watson AI Lab

BMVA Symposium on Vision and Language Wednesday 17 January 2024

All opinions are my own

#MITIBM #AI

UNIVERSITÄT BONN



Vision-Language Learning

Vision-Language learning is the foundation of recent AI breakthroughs: CLIP, Stable diffusion, BLIP, and many more.

Allows for image generation, captioning, text-to image/video retrieval etc ...





Via Contrastive Loss



Via Reconstruction Loss



#MITIBM #AI

UNIVERSITÄT BONN



Source https://openai.com/research/dall-e

Video Understanding – A short history in datasets

Classification



2000







Kinetics 400 / 600 / 700









HT100M

VL-Retreival



Year



HD Vila

InternVid

分かってるわよ待ってティッシュはどこシャワーを買って閃いた まずはこんな風に屠るの(Lunderstand, just wair Whare not

T a man and a bathroom.



Video understanding – How to scale?

The bigger the datasets, the harder to annotate

For a top-down dataset, you need to define action classes.

For a larger dataset, you

1) Need to define and find more action classes

2) Need to define **more distinct** action classes

3) Need to find/record **more videos** with **distinct** action classes



Video understanding – How to scale?

The bigger the datasets, the harder to annotate ...





Lessons learned (2017):

- Classification does not work bottom up
 → might not scale
- Gap between natural language and class labels

Vision-Language Learning for Video

Vision-language models classify data without being trained on the test classes/datasets. \bullet

Setup:



Large-scale training data (e.g. HowTo100M) on audio (A), video (V), text (T) ASR or caption







Vision-Language embedding space

Tasks:

Retrieval (cross-modal) ullet

 \rightarrow Based on distance between reference and test samples

Retrieval related:

- **Zero-shot Classification**
- Zero-shot Temporal • detection/segmentation

Pour the marinade on to the chicken and mix



#MITIBM #AI

UNIVERSITÄT BONN

Why Video Needs Language...

Real-world video understanding can be difficult ...

Actions are not well defined

Perception/labels are subjective, depend on duration, expertise etc.

Actions are unconstrained

They don't have a physical outline

There is no fix/complete "taxonomy" on actionsNot possible to learn a vocabulary

Lack of annotated data

We will never be able to label action data at a \bullet significant (real-world) scale







Recap of works in the field...

Incomplete list:

- HowTo100M: Learning a Text-Video Embedding by Watching Hundred Million Narrated Video Clips [Miech, ICCV 2019]
- End-to-end learning of visual representations from uncurated instructional videos. [Miech, CVPR 2020]
- Selfsupervised multimodal versatile networks. [Alayrac, NeurIPS 2020]
- Self-supervised learning by cross-modal audio-video clustering. [Alwassel, NeurIPS2020]
- Labelling unlabelled videos from scratch with multi-modal self-supervision. [Asano, NeurIPS 2020]
- Frozen in Time: A Joint Video and Image Encoder for End-to-End Retrieval [ICCV 2021]
- MERLOT Reserve: Multimodal Neural Script Knowledge through Vision and Language and Sound [Zellers, CVPR2022]
- Learning Audio-Video Modalities from Image Captions [Nagrani,2022]
- Crossmodal-3600: A Massively Multilingual Multimodal Evaluation Dataset [Thapliyal, 2022]
- Many more ...

#MITIBM #AI

UNIVERSITAT BONN



Miech, ICCV 2019



Alwassel, NeurIPS2020

Recap of our work in the field...

- **AVLnet: Learning Audio-Visual Language Representations from** Instructional Videos [Roudichenko et al., arxiv 2020, Interspeech 2021]
- Multimodal Clustering Networks for Self-supervised Learning ulletfrom Unlabeled Videos [B. Chen et al., ICCV2021]
- Everything at Once Multi-modal Fusion Transformer for Video Retrieval [N. Shvetsova et al., CVPR 2022]
- Preserving Modality Structure Improves Multi-Modal Learning ullet[Sirnam et al., ICCV 2023]









#MITIBM #AI

UNIVERSITAT BON

Vision-Language for (better) Video Understanding

Fixing language for better multimodal learning

Input video: ASR with timestamps: Generated captions:



4s: hi my name's adam pickett 6s: i'm head chef at plateau restaurant in canary wharf and i'm going to show you how to roast carrots 12s: so the actual carrots have lots of sugar inside and once that's roasted those

64s: they're going to take about 15 minutes if you've got a larger carrot 67s: obviously they're going to take a bit longer 69s: so i'm removing my carrots from the oven 71s: what i'm looking for is that lovely caramelization

4s: Adam Pickett introduces himself as the head chef at Plateau Restaurant in Canary Wharf. 6s: He shows how to roast carrots. 12s: The carrots' sugars will caramelize, giving them a lovely sweet flavor.

64s: The person is preparing carrots. 67s: The carrots will take longer to cook. 69s: The person is removing the carrots from the oven 78s: The carrots are ready to be served. 80s: The carrots make a

-

Action Classification in Times of Vision-Language Models



#MITIBM #AI



What, when, and where? Spatial-Temporal Grounding in Videos



Query: Crack eggs Spatial: Find localized action step using open vocabulary text query

Fixing language for better multimodal learning

What's wrong with language in video?

- Language (and topic) domain shift between downstream datasets
- Language domain shift between free training data (ASR subtitles) and downstream datasets (human annotated captions)

Dataset	Exan
MSR-VTT (~43 symbols in a text)	 The difference Southey A
YouCook2 (~39 symbols in a text)	1) Co 2) Gi 3) St
DiDeMo (~147 symbols in a text)	 A Dog dog a plant Or to the ketba dium are si A way. bus di
MSVD (~31 symbols in a text)	1) Th 2) Th 3) A
LSMDC (~46 symbols in a text)	1) SC come on SC 2) He 3) SC

#MITIBM #AI

UNIVERSITAT BONN

nples

he peoples are sharing their view on this car of erent models

omeone is showing the ingredients for a dish are going to make

man is playing an instrument

ombine macaroni sauce and cheese rate and cube potatoes tir in crushed tomatos

dog runs down a hill and stop behind a shrub. sniffs and chews at patch of grass on rock. the approaches, then begins to sniff the cluster of ts first time hand is seen petting dog.

only big screen is visible the camera first pans ne large screen. The view shifts from the basall court to the fans in the seats across the stan. Camera goes to the bigscreens the dancers shown on the jumbotraun.

bus stops. The bus stops at the end of the drive-A kid is coming out of a school bus. School doors open.

he cats are fighting he lady sliced a vegetable man is eating a pizza

OMEONE goes to the kitchen, wets a towel, es back to the bed, kneels it, places the towel OMEONE's brow.

le slaps SOMEONE again.

OMEONE moves off through the crowd.

In-Style: Bridging Text and Uncurated Videos with Style Transfer for Text-Video Retrieval [N. Shvetsova & A. Kukleva et al., ICCV 2023]

Language domain shift in downstream datasets ...

... is not a bug, it's life!

1) Deal with it!

Without training data!





In-Style: Bridging Text and Uncurated Videos with Style Transfer for Text-Video Retrieval [N. Shvetsova & A. Kukleva et al., ICCV 2023]





In-Style: Bridging Text and Uncurated Videos with Style Transfer for Text-Video Retrieval [N. Shvetsova & A. Kukleva et al., ICCV 2023]

Method	Image-Text Datasets	Video-Text Datasets		MSR	-VTT			YouC	Cook2			DiD	eMo			MS	VD			LSM	IDC	
	Intage-Text Datasets	VIdeo-Text Datasets	R 1	R5	R10	MR	R 1	R5	R10	MR	R 1	R5	R10	MR	R 1	R5	R10	MR	R 1	R5	R10	MR
HowTo100M [43]	-	HowTo100M	7.5	21.2	29.6	38	6.1	17.3	24.8	46	-	-	-	-	-	-	-	-	-	-	-	-
SupportSet [48]	-	HowTo100M	8.7	23.0	31.1	31	-	-	-	-	-	-	-	-	8.9	26.0	37.9	18	-	-	- 1	-
VATT [1]		HowTo100M+AS	-	-	29.7	49	-	-	45.5	13	· - ·	-	-	-	-	-	-	-	-	-	-	-
EAO [§] [55]	-	HowTo100M	9.9	24.0	32.6	28	19.8	42.9	55.1	8	6.6	19.0	26.8	42	18.0	40.4	52.3	9	3.6	8.5	13.0	177
Nagrani et al. [45]	-	VideoCC3M	19.4	39.5	50.3	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
Frozen in Time [3]	CC+COCO	WebVid-2M	24.7	46.9	57.2	7	-		1.7	-	21.1	46.0	56.2	7	-	-	-	-	-	-	-	
CLIP-straight [49]	WIT	-	31.2	53.7	64.2	4	-	-	-	-	-	-		-	37.0	64.1	73.8	2	11.3	22.7	29.2	56.5
CLIP4CLIP [38]	WIT	HowTo100M	32.0	57.0	66.9	4	-	_	12	<u> </u>	-	-	-	-	38.5	66.9	76.8	2	15.1	28.5	36.4	28
Nagrani et al. [45]	WIT	VideoCC3M	33.7	57.9	67.9	-	-	_	-	20	-	-	-	-	-	-	-	-	-	-	_	-
BLIP [31]	CC+COCO+3more*	-	33.3	57.3	67.5	3.5	5.8	15.0	21.9	76	24.6	50.4	59.7	5.3	37.0	63.3	72.6	3	15.2	28.2	35.9	35
In-Style (ours) (CLIP)	WIT	HowTo100M ^{\dagger} +VATEX ^{\ddagger}	35.0	59.6	70.4	3	5.1	14.0	20.3	103	26.6	50.5	62.6	5	38.6	66.3	77.9	3	16.0	31.6	38.5	26.5
In-Style (ours) (BLIP)	CC+COCO+3more*	HowTo100M [†] +VATEX [‡]	36.0	61.9	71.5	3	6.8	16.7	24.5	63	29.4	59.2	68.6	3.5	44.9	72.7	81.1	2	16.4	30.1	38.7	28
In-Style (ours) (BLIP)	CC+COCO+3more*	HowTo100M [†] +WikiHow	34.2	59.6	69.0	3	7.3	19.2	27.1	46	29.7	56.2	67.4	4	42.8	70.2	79.1	2	17.0	30.8	39.6	27
In-Style (ours) (BLIP)	CC+COCO+3more*	HowTo100M [†] +Food.com	32.8	54.9	65.8	4	7.2	19.8	27.9	47	25.7	52.8	63.1	5	39.5	64.9	74.9	2	14.5	28.9	37.2	30.5
In-Style (ours) (BLIP)	CC+COCO+3more*	HowTo100M [†] +Target [‡]	36.2	61.8	71.9	3	8.6	21.6	30.0	37	32.1	61.9	71.2	3	44.8	72.5	81.2	2	16.1	33.6	39.7	25
In-Style (ours) (EAO)	-	HowTo100M+Target [‡]	16.4	35.8	48.9	10	20.3	46.4	58.8	7	13.2	31.6	44.0	15	23.4	50.0	62.4	5	4.9	12.3	16.7	94



HowToCaption: Prompting LLMs to Transform Video Annotations at Scale (N. Shvetsova & A. Kukleva et al., arxiv)

Convert noisy ASR subtitles of instructional videos into video captions → high-quality video captions at scale without human supervision





HowToCaption: Prompting LLMs to Transform Video Annotations at Scale (N. Shvetsova & A. Kukleva et al., arxiv)

HowToCaption – LLM Prompting + Filtering + Alignment

Caption Post-processing	YouC	Cook2	MSR	-VTT	MS	VD	
	R10↑	MR↓	R10↑	MR↓	R10↑	MR↓	R1
Lower bound: original ASR as supervision	39.3	20	61.7	5	77.1	2	31
No post-processing	40.2	18	65.9	4	79.8	2	34
Filtering (using BLIP)	42.5	16	71.2	3	81.7	2	37
Filtering&alignment (using BLIP)	42.4	17	71.7	3	82.2	2	38
Filtering&alignment (with ours)	44.1	15	73.3	3	82.1	2	38





Problem: Why is CLIP bad on Kintetics?

- \rightarrow Vocabulary gap between VL pretrained models and action classification
- → Usually fixed by fine-tuning with GT

Idea: Can we fix it without annotations?





Input:

- Videos (without labels), Vocabulary (without videos), Pretrained VL / LLM model \bullet Idea:
- Construct a bag of text samples from vocabulary ightarrow
- Match bag of text samples via Multiple Instance Loss \rightarrow MIL-NCE lacksquare







Text Bag Options: 1) Preselect best vocabulary matches via VL model 2) Use LLM to create synonyms, rephrasing etc. 3) Use captioner to generate more samples





Results:

Method	gt	language	vis.encoder	frames	UCF101	HMDB51	K600 Top1	K600 Top5
ER-ZSAR [7]	yes	Manual description	TSM	16	51.8 ± 2.9	35.3 ± 4.6	42.1 ± 1.4	73.1 ± 0.3
JigsawNet [34]	yes	Manual description	R(2+1)D	16	56.0 ± 3.1	38.7 ± 3.7	-	-
ActionCLIP [47]	yes	K400 dict.	ViT-B/16	32	58.3 ± 3.4	40.8 ± 5.4	66.7 ± 1.1	91.6 ± 0.3
XCLIP [33]	yes	K400 dict.	ViT-B/16	32	72.0 ± 2.3	44.6 ± 5.2	65.2 ± 0.4	86.1 ± 0.8
A5 [18]	yes	K400 dict.	ViT-B/16	32	69.3 ± 4.2	44.3 ± 2.2	55.8 ± 0.7	81.4 ± 0.3
ViFi-CLIP [38]*	yes	K400 dict.	ViT-B/16	16	74.9 ± 0.6	50.9 ± 0.7	67.7 ± 1.1	90.8 ± 0.3
ViFi-CLIP [38]	yes	K400 dict.	ViT-B/16	32	76.8 ± 0.7	51.3 ± 0.6	71.2 ± 1.0	92.2 ± 0.3
Text4Vis [50]	yes	K400 dict.	ViT-L/14	16	-	-	68.9 ± 1.0	-
CLIP [36]	no	-	ViT-B/16	16	69.9 ± 1.3	38.0 ± 1.7	63.5 ± 0.4	86.8 ± 0.4
MAXI	no	K400 dict.	ViT-B/16	16	76.6 ± 0.9	50.5 ± 0.9	70.4 ± 0.8	91.5 ± 0.3
MAXI	no	K400 dict, GPT3 verbs	ViT-B/16	16	77.8 ± 0.3	51.6 ± 0.9	71.6 \pm 1.0	92.3 ± 0.3
MAXI	no	K400 dict, GPT3 verbs	ViT-B/16	16/32	$\overline{77.8} \pm 0.5$	51.9 ± 1.1	71.6 ± 1.0	92.4 ± 0.3
MAXI	no	K400 dict, GPT3 verbs, BLIP verbs	ViT-B/16	16	78.2 ± 0.8	52.2 ± 0.6	71.4 ± 0.9	$\overline{92.5} \pm 0.3$
MAXI	no	K400 dict, GPT3 verbs, BLIP verbs	ViT-B/16	16/32	78.2 ± 0.8	$\overline{52.3} \pm 0.7$	$\underline{71.5} \pm 0.8$	$\textbf{92.5}\pm0.4$

Zero-shot action recognition on UCF101, HMDB51 and K600, CLIP fine-tuned with K400 vocabulary + videos



Results:

Action dictionary	dictionary size	UCF101	HMDB51	K600	MiniSSv2	Charades	UAV Human	Moments-in-time
CLIP [36] (w/o finet	une) Zero-Shot	69.93 / 92.7	38.02 / 66.34	63.48 / 86.80	3.96 / 14.42	19.80	1.79 / 7.05	20.11 / 40.81
K400 MiniKinetics K400+WebVid2.5M	400 200 800	78.18 / 96.03 75.10 / 95.82 <u>75.99</u> / <u>96.00</u>	50.35 / 77.10 <u>48.34</u> / <u>76.95</u> 45.97 / 73.94	70.78 / 92.17 <u>69.23</u> / 90.92 69.14 / <u>91.13</u>	<u>5.74</u> / <u>17.70</u> 6.50 / 18.76 4.81 / 15.79	23.89 <u>22.70</u> 22.67	3.06 / 9.46 <u>2.40 / 8.04</u> 2.11 / 8.00	<u>22.41</u> / <u>45.83</u> 22.50 / 46.01 20.92 / 43.99

Zero-shot action recognition with CLIP fine-tuned with K400 videos + other vocabulary (mAP on Charades and Top1/Top5 accuracy on other datasets).



How to understand what's going on?

What, when, and where? - Self-Supervised Spatio-Temporal Grounding in Untrimmed Multi-Action Videos from Narrated Instructions [B. Chen et al., arxiv]





#MITIBM #AI



Task: Spatio-Temporal Grounding - Find the temporal boundary of an open vocabulary queried action in an untrimmed video and spatially localize the action.

What, when, and where? - Self-Supervised Spatio-Temporal Grounding [B. Chen et al., arxiv]

Datasets:

YouCook2-Interactions Dataset

- \rightarrow frame-level bounding boxes for instructional cooking videos
- \rightarrow annotations for on YouCook2 validation split
- \rightarrow trimmed clips only

Grounding YouTube (coming soon)

- frame-level point clouds and bounding boxes for cooking videos
- \rightarrow annotations for mining YouTube
- \rightarrow Untrimmed spatial-temporal grounding









#MITIBM #AI





Look at What I am Doing: Self-Supervised Spatial Grounding of Narrations in Instructional Videos; Reuben Tan, Bryan A. Plummer, Kate Saenko, Hailin Jin, Bryan Russell, NeurIPS2021

https://cs-people.bu.edu/rxtan/projects/grounding_narrations/

What, when, and where? - Self-Supervised Spatio-Temporal Grounding [B. Chen et al., arxiv]

Idea:

- Local information better at capturing spatial information
- Global information better at capturing temporal information
- Add frame selection for efficiency





What, when, and where? - Self-Supervised Spatio-Temporal Grounding [B. Chen et al ., arxiv]

Challenge: Capture (long) temporal and single-frame spatial boundaries \rightarrow --> One branch for global representation learning \rightarrow start-end frame --> One branch for local, spatial representation learning \rightarrow bounding box





(b) Spatial grounding

Attention Scores +0.0

→0.7 ▶0.0 **→**0.1 -- 0.5



What, when, and where? - Self-Supervised Spatio-Temporal **Grounding** [B. Chen et al., arxiv]

Results: Spatial-Temporal Grounding

	DUU	Deterio	G					m	AP		
Method	Backdone	DataSet	Supervision	Modality	100+Pollit	0.1	0.2	0.3	0.4	0.5	0.1:0.5
CoMMA† [45]	S3D	HT250K	Self	VT	1.02	2.18	1.72	1.11	0.93	0.37	1.26
MIL-NCE [35]	S3D*	HT100M	Self	VT	4.67	33.94	25.16	12.65	3.42	0.41	15.11
Ours	S3D	HT100M	Self	VT	9.12	42.70	35.49	25.16	16.22	10.05	25.92
GLIP [30]	Swin-L*	Cap24M	Weak	IT	1.24	2.83	2.10	1.52	0.96	0.37	1.56
CoMMA‡ [45]	CLIP	HT100M	Self	VT	1.68	3.51	2.32	1.88	0.99	0.40	1.82
CLIP [37]	CLIP	HT100M	Self	IT	3.59	29.54	22.15	9.16	2.48	0.39	12.74
RegionCLIP [61]	ResNet-101*	CC3M	Weak	IT	5.65	35.65	27.43	15.69	4.31	0.86	16.78
Ours	CLIP	HT100M	Self	VT	10.09	42.81	36.05	25.84	17.10	11.35	26.63
Ours	CLIP*	HT100M	Self	VT	11.53	43.64	36.94	26.78	19.45	14.61	28.26
MIL-NCE(temp.)+RegionCLIP(spa.)	-	-	-	VT	9.21	40.54	34.97	22.38	13.79	9.18	22.33



Groun	ding	Youtu	ıbe
-------	------	-------	-----

What, when, and where? - Self-Supervised Spatio-Temporal **Grounding** [B. Chen et al., arxiv]

Results: Spatial Grounding only

	YC-Inter GroundingY		dingYT	V-H	D	aly					
Method	Backbone	Data	Super.	Mod.	Acc	Acc	mAP	Acc	mAP	Acc	m
MIL-NCE [35] CoMMA† [45] Ours	S3D* S3D S3D	HT100M HT250K HT100M	Self Self Self	VT VT VT	23.67 48.63 53.98	27.45 47.68 60.62	8.21 23.38 44.93	12.65 40.97 44.32	11.23 21.45 24.31	13.84 54.48 66.35	24 33 45
CLIP [37] CoMMA‡ [45] RegionCLIP [61] GLIP [30] Ours Ours	CLIP CLIP RN50x4* Swin-L* CLIP CLIP*	HT100M HT100M CC3M Cap24M HT100M HT100M	Self Self Weak Weak Self Self	IT VT IT IT VT VT	14.10 52.65 51.56 52.84 57.10 58.35	12.50 47.56 52.84 53.62 55.49 56.98	3.49 36.42 23.42 24.73 43.12 45.32	29.23 55.20 57.92 66.05 60.71 62.34	12.51 34.54 37.82 41.17 39.28 41.56	18.02 61.06 67.12 - 70.08 71.35	27 44 48 50 52
TubeDETR [53] STCAT [23]	MDETR ResNet-101	Vid-STG Vid-STG	Full Full	VT VT	51.63 54.47	53.24 55.90	41.76 44.21	63.23 65.34	40.87 41.10	84.21 85.42	62 63





Vision-Language in Video – What's next?

Pro:

No more labels! No more annotation!

- \rightarrow Natural language requests for video systems (retrieval, detection, etc.)
- → Natural language representations of video

... will lead to new applications in video understanding

#MITIRM #AT



Vision-Language in Video – What's next?

Con:

No more simple metrics! (retrieval might already be ceiling) No more simple comparability!

Before: Classification accuracy on 2-3 standard datasets

Now: Various mixtures of pretraining and downstream testing \rightarrow How do we know what works better?

#MITIRM #AT



People at a glance ...



Nina Shvetsova Goethe University Frankfurt



Anna Kukleva MPII Saarbruecken



Wei Lin TU Graz



Bernt Schiele MPII Saarbrucken



Christian Rupprecht Oxford



Horst Bishof TU Graz

#MITIBM #AI





Brian Chen Meta/Columbia University

Thanks for listening!



How to understand what's going on?

What, when, and where? - Self-Supervised Spatio-Temporal Grounding in Untrimmed Multi-Action Videos from Narrated Instructions [B. Chen et al., arxiv 2023]











#MITIBM #AI



Evaluation Setup: Referential queries - "Crack egg", "Mix egg", etc.

Task: Spatio-Temporal Grounding - Find the temporal boundary of a queried action in an untrimmed video and *spatially localize* the action.

What, when, and where? - Self-Supervised Spatio-Temporal Grounding [B. Chen et al., arxiv 2023]

Datasets:

YouCook2-Interactions Dataset

- \rightarrow frame-level bounding boxes for instructional cooking videos
- Annotations for on YouCook2 validation split
- \rightarrow trimmed clips only

Grounding YouTube

 \rightarrow frame-level point clouds and bounding boxes for cooking videos

- \rightarrow annotations for mining YouTube
- \rightarrow Untrimmed spatial-temporal grounding





#MITIBM #AI



Look at What I am Doing: Self-Supervised Spatial Grounding of Narrations in Instructional Videos; Tan et al., NeurIPS2021



What, when, and where? - Self-Supervised Spatio-Temporal Grounding [B. Chen et al., arxiv]

Idea:

- Local information better at capturing spatial information
- Global information better at capturing temporal information
- Add frame selection for efficiency





What, when, and where? - Self-Supervised Spatio-Temporal Grounding [B. Chen et al., arxiv]

Challenge: Capture (long) temporal and single-frame spatial boundaries \rightarrow --> One branch for global representation learning \rightarrow start-end frame --> One branch for local, spatial representation learning \rightarrow bounding box



#MITIBM #AI



(b) Spatial grounding

Attention Scores +0.0

→0.7 ▶0.0 **→**0.1 -- 0.5



What, when, and where? - Self-Supervised Spatio-Temporal Grounding [B. Chen et al., arxiv]

Results:

- Sota results for spatio-temporal localization in untrimmed videos
- Global + local information also single tasks
- Smart frame selection helps

							Groun	dingYout	ube		
Method	Backhone	DataSet	Supervision	Modelity	IoII+Point			m	AP		
	Dackbone	DataSet	Super vision	mouanty	100 11 0111	0.1	0.2	0.3	0.4	0.5	0.1:0.5
CoMMA [†] (Tan et al., 2021)	S3D	HT250K	Self	VT	1.02	2.18	1.72	1.11	0.93	0.37	1.26
MIL-NCE (Miech et al., 2020)	S3D*	HT100M	Self	VT	4.67	33.94	25.16	12.65	3.42	0.41	15.11
Ours	S3D	HT100M	Self	VT	9.12	42.70	35.49	25.16	16.22	10.05	25.92
GLIP (Li et al., 2022a)	Swin-L*	Cap24M	Weak	IT	1.24	2.83	2.10	1.52	0.96	0.37	1.56
CoMMA‡ (Tan et al., 2021)	CLIP	HT100M	Self	VT	1.68	3.51	2.32	1.88	0.99	0.40	1.82
CLIP (Radford et al., 2021)	CLIP	HT100M	Self	IT	3.59	29.54	22.15	9.16	2.48	0.39	12.74
RegionCLIP (Zhong et al., 2022)	ResNet-101*	CC3M	Weak	IT	5.65	35.65	27.43	15.69	4.31	0.86	16.78
Ours	CLIP	HT100M	Self	VT	10.09	42.81	36.05	25.84	17.10	11.35	26.63
Ours	CLIP*	HT100M	Self	VT	11.53	43.64	36.94	26.78	19.45	14.61	28.26
MIL-NCE(temp.)+RegionCLIP(spa.)	-	-	-	VT	9.21	40.54	34.97	22.38	13.79	9.18	22.33

only Local le only Global w/ Both loss





	GroundingYT Spatio-temporal	MiningYT Temporal	YouCook-Inter. Spatial
	15.1	17.8	55.5
ction	15.7	18.5	54.3
ion	15.6	18.1	56.3
	17.1	19.9	57.1
oss	5.7	4.5	54.3
loss	7.6	18.8	32.5
5	17.1	19.9	57.1



